## Xsens DOT Firmware Changelogs

Author: Product Manager Last updated: August 24, 2020 Document: XD0207P



Symbol	Meaning
+	Added
^	Changed
!	Note
#	Fixed
-	Removed

Version 1.4.0

### Release date: August 24, 2020

#### **Release type: Stable**

#### Compatible App and SDK versions: 2020.2

+ Added notification when entering power saving mode in connection mode.

+ Support 4 new payload modes with both sensor fusion and inertial data.

+ Added recording function to enable data recording and exporting with sensor internal storage.

- + Added synchronization function to have the time-synced data.
- + Added serial number support.
- ^ Battery shelf life has been improved.
- ^ Changed all the big endianness settings to little endianness.
- ^ Improved the filter profile to reduce the heading drift after fast movement.
- Removed the UUID in advertisement packet.
- # Removed the 2nd notification when starting OTA in uncharged status.

# Fixed the NaN value output after sensor disconnect and connect again in real-time streaming.

# Fixed the wrong angular velocity and acceleration output in Delta quantities and Rate quantities modes.

Version 1.3.0

#### Release date: April 24, 2020

#### **Release type: Beta**

### Compatible APK and SDK versions: 2020.1

^ Introducing 12 new measurement modes with support to different measurement quantities to reduce payload demands on BLE transmission.

^ The device's Bluetooth transmit power has been increased.

^ The transmit buffering has been increased to cope with any transient data loss.

+ Euler angles, delta\_q, delta\_v, angular velocity and acceleration data quantities have been added to the data output options.

- + Heading reset feature support.
- + Support for saving firmware crash logs has been added.
- + Xsens Bluetooth company ID.
- Support to FW v1.0.0 'Default' measurement mode has been removed.
- # Firmware crash associated with a packet counter reset has been fixed.



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# Fixed the issue where OTA could not be started after heat protection kicked in.

# Reset issue of sensor fusion filter upon starting measurement has been fixed.

